

Linear Single Cell Li-Ion Battery Charger with Power Path Management and I²C-Control

General Description

ET9562 is a linear single cell Li-ion battery charger integrated power path management. The charger uses a CC/CV charge profile required by Li-ion battery. It also accepts an input voltage up to 24V and will cut off rapidly when the input voltage exceeds OVP threshold (Typically 6.0V). The charger features trickle charge, constant current and constant voltage regulation, charge termination, and charge status.

The internal Power Path Management can balance the input current to system and battery, which ensures continuous power to the system from input, battery or both. Also ET9562 integrates dynamic power management. When system load is heavy, the charge current will be reduced to keep input current or input voltage in regulation.

ET9562 provides over-current protection from input to the system and battery to the system. This can prevent the Li-on battery from being damaged by excessively high current. Input and battery under-voltage lockout (UVLO) will cuts off the load path when power supply is unstable. An integrated I²C control interface allows the ET9562 to program the critical parameters, such as battery constant voltage, constant charge current, trickle charge threshold, battery regulation voltage, battery UVLO, input voltage regulation, input current regulation, and system voltage regulation.

The ET9562's high integration can simplify system design and reduce the number of components outside. The device is packaged in advanced Full-Green compliant WCSP package.

Features

- 24V Maximum Rating for VIN Power
- Internal 6.0V Over Input Voltage Protection
- Fully Autonomous Charger for Single-Cell Li-on Battery
- Auto Power Path Management for Powering the System and Charging the Battery
- Integrated Power MOSFETs for System load and Charging Mode
- $\pm 0.5\%$ Charging Voltage Accuracy
- I²C Interface for Setting Parameters
- Built-In input and battery UVLO Protection
- Thermal Limiting Regulation On-Chip
- Outside OTP Sensing by NTC pin

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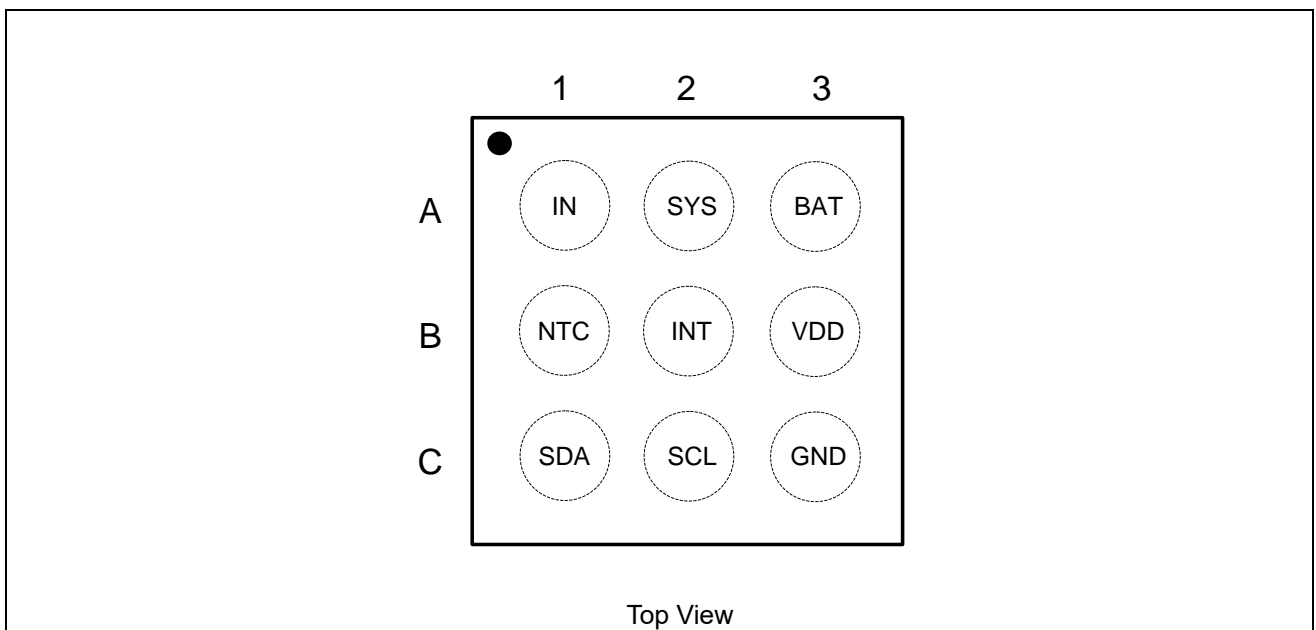
Device Information

Part No.	Package	MSL
ET9562	CSP9(1.69mm×1.69mm)	Level 1

Application

- Smart Watches
- Wearable Devices
- IP Camera

Pin Configuration

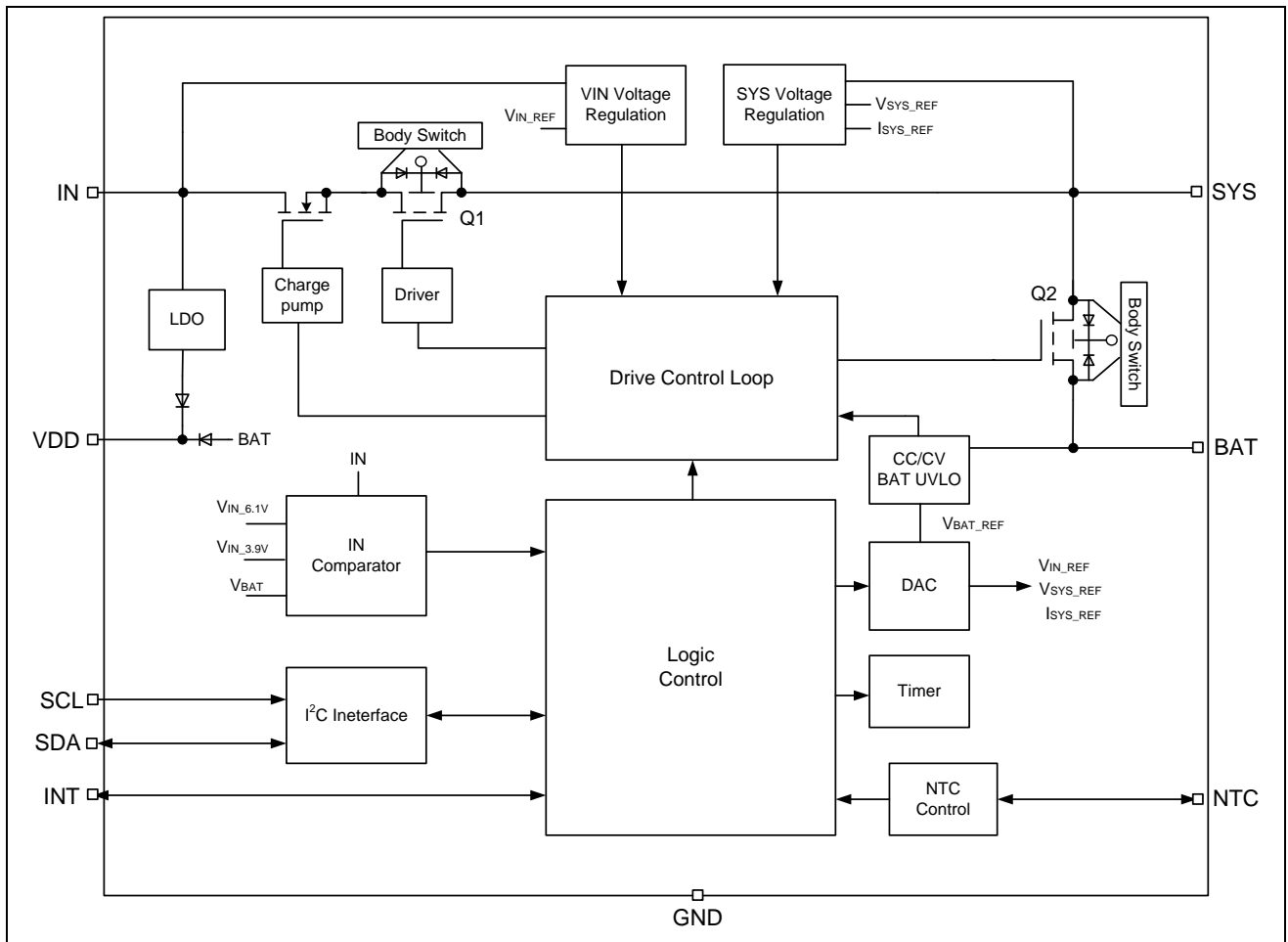


Pin Function

Pin No.	Pin Name	Description
A1	IN	Power Supply Input Pin.
A2	SYS	System Connect Pin.
A3	BAT	Charge Output Pin.
B1	NTC	Thermal sense Pin.
B2	INT	Open Drain interrupt output.
B3	VDD	Internal control power supply.
C1	SDA	I ² C interface data.
C2	SCL	I ² C interface clock.
C3	GND	Ground.

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Block Diagram



Functional Description

ET9562 is a linear single cell Li-ion battery charger integrated power path management. The charger uses a CC/CV charge profile required by Li-ion battery. It also accepts an input voltage up to 24V and will cut off rapidly when the input voltage exceeds OVP threshold (Typically 6.0V). The charger features trickle charge, constant current and constant voltage regulation, charge termination, and charge status.

The internal Power Path Management can balance the input current to system and battery, which ensures continuous power to the system from input, battery or both. It allows for separate control between the system and the battery, and has high priority to power supply system.

The internal Dynamic Power Management can regulate the input voltage to V_{IN_REG} when the load is over the input power capacity. The charge current is reduced to keep the input current or input voltage in regulation when DPM occurs. If the charge current is at zero and the input source is still over-loaded, system voltage starts to fall down. Once the system voltage falls below the battery voltage, ET9562 enters battery supplement mode.

ET9562 provides over-current protection from input to the system and battery to the system. This can prevent the Li-on battery from being damaged by excessively high current. Input and battery under-voltage lockout (UVLO) will cut off the load path when power supply is unstable. An integrated I²C control interface allows the ET9562 to program the critical parameters, such as battery constant voltage, constant charge current, trickle charge threshold, battery regulation voltage, battery UVLO, input voltage regulation, input current regulation, and system voltage regulation.

ET9562 include Battery Discharge Mode, Battery Supplement Mode, Battery Charge Mode, Only Power System Mode and Shipping Mode, [Figure 1](#) is shown the internal state machine conversion.

- (1) Battery Discharge Mode: Only Battery to SYS Path is enabled.
- (2) Battery Supplement Mode: IN to SYS path and Battery to SYS path are enabled.
- (3) Battery Charge Mode: IN to SYS path and IN to Battery path are enabled.
- (4) Only Power System Mode: Only IN to SYS Path is enabled.
- (5) Shipping Mode: All paths are disabled, ET9562 enters into low power consumption state.

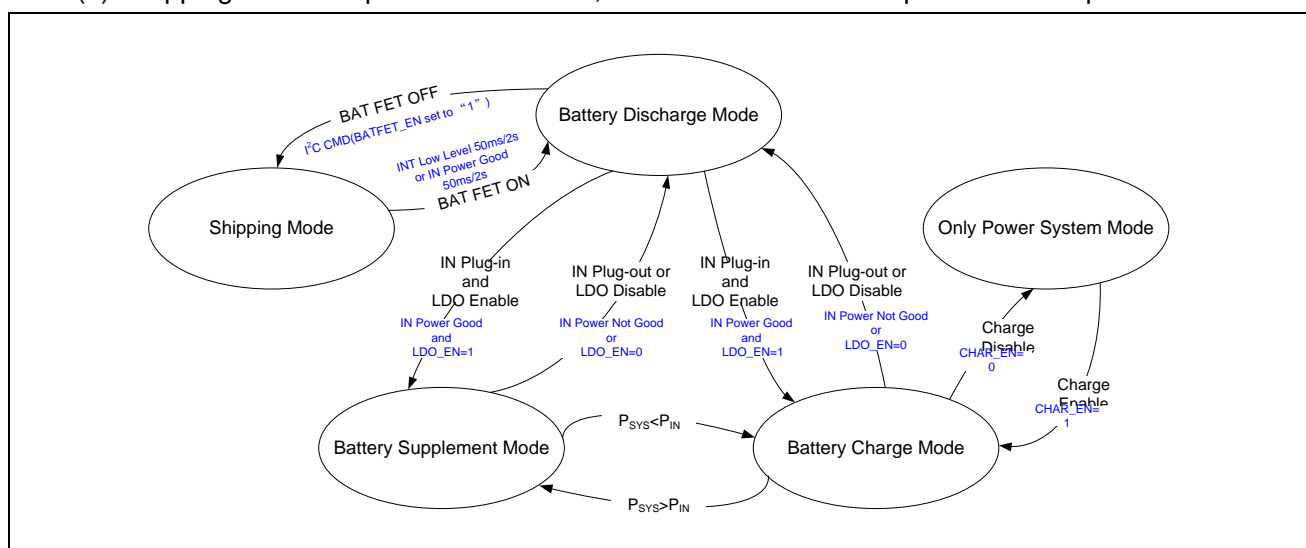


Figure 1. State Machine Conversion

Power Supply

The internal bias circuit of the IC is powered from the higher voltage of IN or BAT. When IN or BAT rises above the respective under voltage lockout (UVLO) threshold, the sleep comparator, battery depletion comparator, and the battery MOSFET driver are active. After 2ms, the I²C interface is ready for communication and all registers are reset to the default value. The host can access all registers.

Input OVP and UVLO

The ET9562 has an input over-voltage protection (OVP) threshold and an input UVLO threshold. Once the input voltage exits the normal input voltage range, the Q1 MOSFET is turned off immediately.

When the input voltage is identified as a good source, a 450us immunity timer is active. If the input power is still sufficient until the 450us timer expires, the system starts up. Otherwise, Q1 remains off. Figure 2 depicts the operation profile.

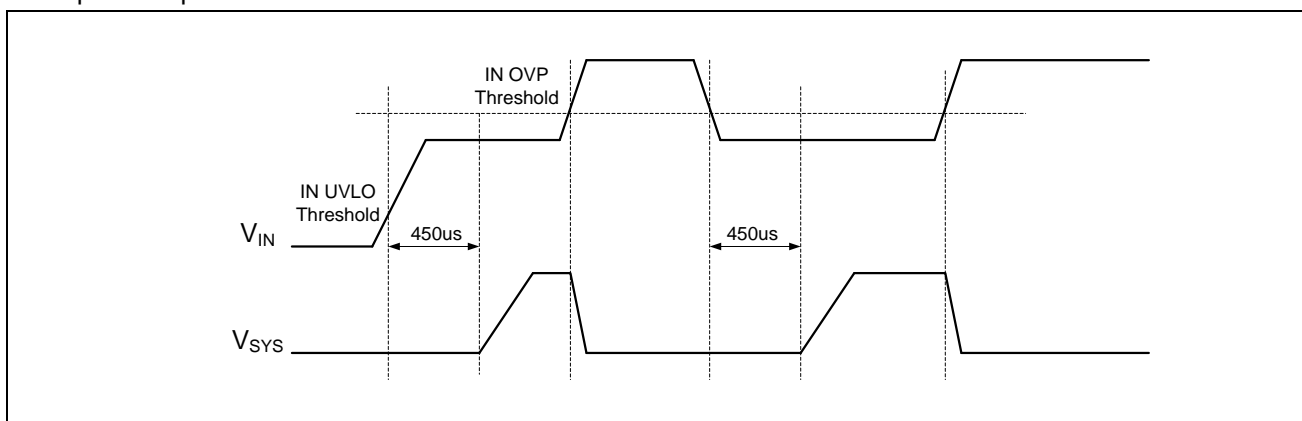


Figure 2. Input Power Detection Operation Profile

Power Path Management

The IC employs a direct power path structure with the battery MOSFET decoupling the system from the battery, which allows for separate control between the system and the battery. The system is given the priority to start up even with a deeply discharged or missed battery. When the input power is available, even with a depleted battery, the system voltage is always regulated to V_{SYS_VSET} by the integrated LDO MOSFET. The system voltage can be programmable via Reg09[5:3], and the system voltage must higher than $V_{BAT_REG}+200mV$.

As shown in Figure 3, the direct power structure is composed of a frond-end LDO MOSFET between IN and SYS and a battery FET between SYS and BAT.

The input LDO (using an LDO MOSFET) provides power to the system, which drives the system load directly and charges the battery through the battery FET. And the input LDO can be changed to switch mode by setting Reg01[4]=1.

For the system voltage control, when the input voltage is higher than V_{SYS_REG} , the system voltage is regulated to V_{SYS_REG} . When the input voltage is lower than V_{SYS_REG} , the LDO MOSFET is fully on with the input current limit.

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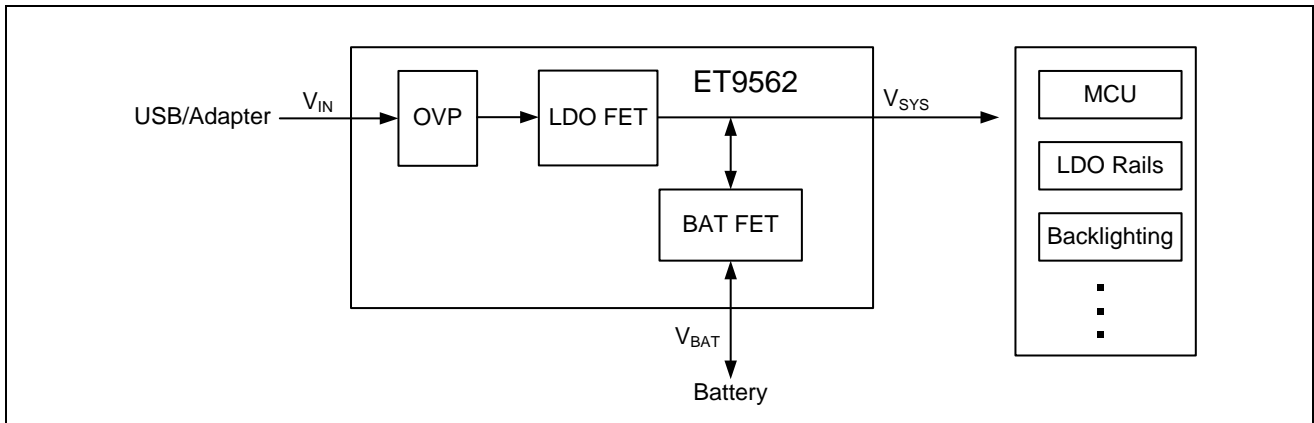


Figure 3. Power Path Management Structure

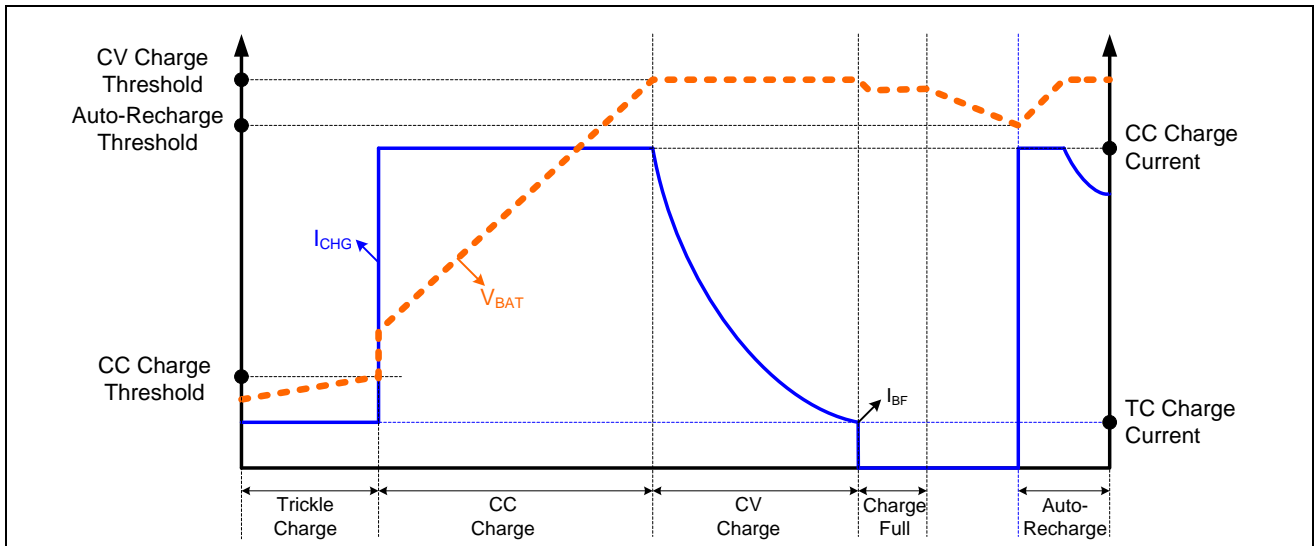


Figure 4. Battery Charge Profile

Battery Charge Profile

The IC provides three main charging phases: trickle charge, constant current charge, and constant voltage charge (see [Figure 4](#)).

Phase 1 (trickle current charge): The IC is able to safely trickle charge the deeply depleted battery until the battery voltage reaches the trickle charge to the fast charge threshold (V_{BAT_LOW}). The trickle charge current is programmable via Reg09[2:0]. If V_{BAT_LOW} is not reached before the precharge timer (1hr) expires, the charge cycle is ceased, and a corresponding timeout fault signal is asserted.

Phase 2 (constant current charge): When the battery voltage exceeds V_{BAT_LOW} , the IC enters a constant-current charge (fast charge) phase. The fast charge current can be programmable via Reg02[5:0].

Phase 3 (constant voltage charge): When the battery voltage rises to the programmable charge full voltage (V_{BAT_REG}) set via Reg04 bit [7:2], the charge mode changes from CC mode to CV mode, and the charge current begins to taper off.

Assuming the termination function (BF_EN) is set via Reg05[6] = 1, the charge cycle is considered complete when the following conditions are valid:

- The charge current (I_{BAT}) reaches the end of charge (EOC) current threshold (I_{BF}), and the 250ms delay timer is initiated.
- During the 250ms delay period, I_{BAT} is always smaller than I_{BF} .

The charge status is marked as complete once the 250ms delay timer expires.

The charge current is terminated at the same time if `TERMI_TEN` is set via `Reg05[0] = 0`; otherwise, the charge current keeps tapering off.

If `BF_EN=0`, the termination function is disabled, the above actions will not occur. During the charging process, the actual charge current may be less than the register setting due to other loop regulations, such as dynamic power management (DPM) regulation (input voltage, input current) or thermal regulation. If the input current or the input voltage reach their limits during the CV charge, the charge full termination is not influenced when the charge current is not so close to the EOC current specification.

A new charge cycle starts when the following conditions are valid:

- The input power is recycled
- Battery charging is enabled by the I²C
- Auto-recharge kicks in

Under the following conditions:

- No thermistor fault at NTC
- No safety timer fault
- No battery over-voltage
- BATFET is not forced to turn off

Automatic Recharge

When the battery is fully charged and the charging is terminated, the battery may be discharged due to system consumption or self discharge. When the battery voltage is discharged below the recharge threshold, and `VIN` is still in the operation range, the IC begins another new charging cycle automatically without the requirement of restarting a charging cycle manually.

The auto-recharge function is valid only when `BF_EN=1` and `TERMI_TEN=0`.

Battery Over-Voltage Protection (OVP)

The IC is designed with a built-in battery over-voltage limit about 130mV higher than `VBAT_REG`. When the battery over-voltage event occurs, the IC suspends the charging immediately and asserts a fault.

Input Current and Input Voltage Based Power Management

To meet the input source (usually USB) maximum current limit specification, the IC uses input current-based power management by monitoring the input current continuously. The total input current limit can be programmed via the I²C to prevent the input source from overloading.

If the pre-set input current limit is higher than the rating of the input source, back-up input voltage-based power management also works to prevent the input source from being overloaded. If either the input current limit or the input voltage limit is reached, the Q1 MOSFET between `IN` and `SYS` are regulated so that the total

input power is limited. As a result, the system voltage drops. Once the system declines to the minimum value of $V_{SYS-90mV}$ or $V_{IN-160mV}$, the charge current is reduced to prevent the system voltage from dropping further.

Voltage-based DPM regulates the input voltage to V_{IN_REG} when the load is over the input power capacity. V_{IN_REG} set via the I²C should be at least 400mV higher than V_{BAT_REG} to ensure the stable operation of the regulator.

Battery Supplement Mode

The charge current is reduced to keep the input current or input voltage in regulation when DPM occurs. If the charge current is at zero, and the input source is still overloaded due to a heavy system load, the system voltage starts to fall off. Once the system voltage falls below the battery voltage, the IC enters battery supplement mode. When the system voltage is 30mV below the battery voltage, the ideal diode mode is enabled. The battery MOSFET is regulated to maintain $V_{BAT}-V_{SYS}$ at 22.5mV. If the supplement current $I_{DSG} \cdot R_{ON_BAT}$ is higher than 22.5mV, the battery MOSFET is fully turned on to keep the ideal forward voltage. When the system load decreases, once V_{SYS} is higher than $V_{BAT}+20mV$, ideal diode mode is disabled.

Figure 5 shows the dynamic power management and battery supplement mode operation profile.

When V_{IN} is not available, the IC operates in discharge mode, and the battery MOSFET is always fully on to reduce loss.

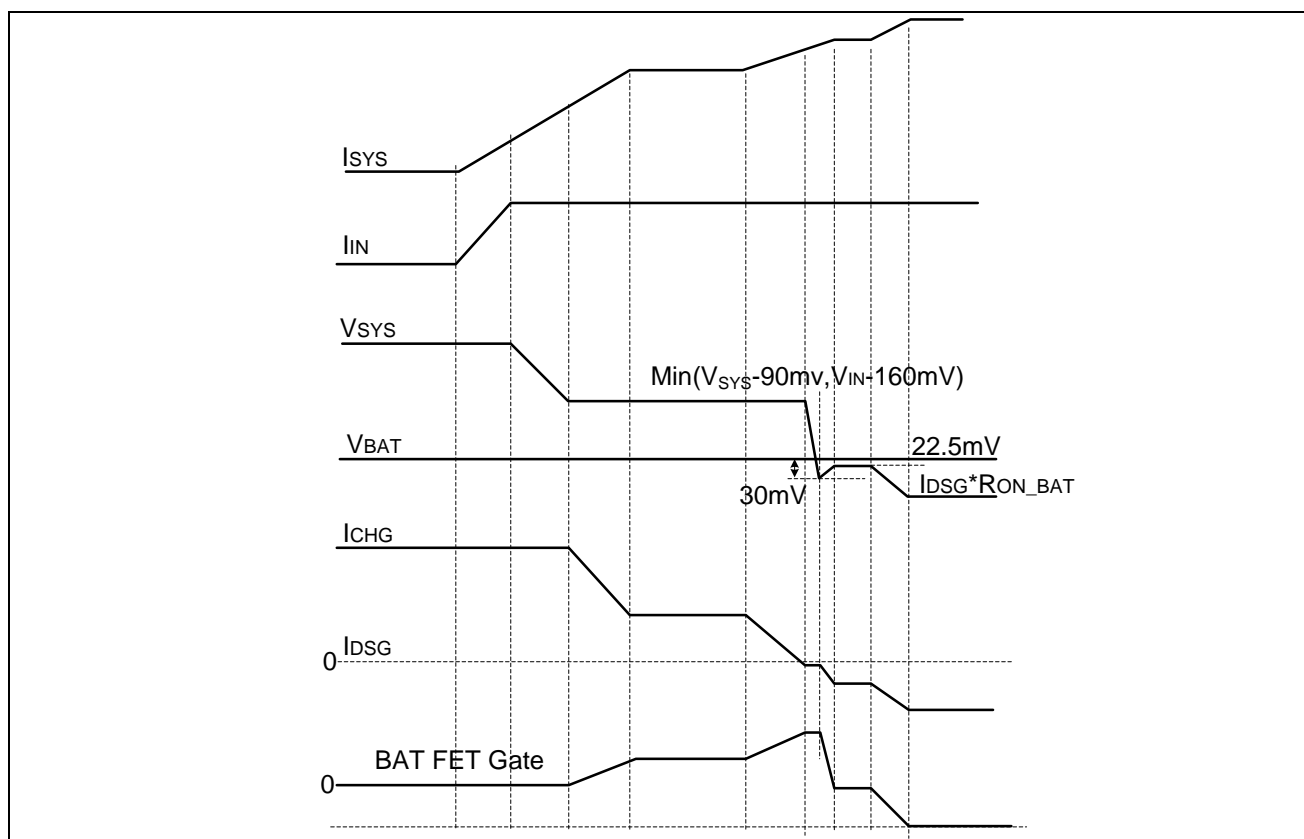


Figure 5. Dynamic Power Management and Battery Supplement Operation Profile

Battery Charge Full Voltage

The battery voltage for the constant voltage regulation phase is V_{BAT_REG} . When V_{BAT_REG} is 4.2V, it has a $\pm 0.5\%$ accuracy over the ambient temperature range of 0°C to +50°C. When the battery is removed, the BAT voltage is between $V_{BAT_REG}-V_{RECHG}$ and V_{BAT_REG} .

Thermal Regulation and Thermal Shutdown

The IC monitors the internal junction temperature continuously to maximize power delivery and prevent the chip from overheating.

When the internal junction temperature reaches the pre-set limit of T_{REG} (default 120°C), the IC reduces the charge current to prevent higher power dissipation. The multiple thermal regulation thresholds from 60°C to 120°C help the system design meet the thermal requirement in different applications. The junction temperature regulation threshold can be set via Reg06 bit [1:0].

When the junction temperature reaches 150°C, IN to SYS path and SYS to BAT path will be closed. But the BAT to SYS discharge path is still open.

Negative Temperature Coefficient (NTC) Temperature Sensor

NTC allows the IC to sense the battery temperature using the thermistor usually available in the battery pack to ensure a safe operating environment for the chip. A resistor with an appropriate value should be connected from VDD to NTC, and the thermistor should be connected from NTC to ground. The voltage on NTC is determined by the resistor divider, whose divide ratio depends on the temperature. The IC sets a pre-determined upper and lower bound of the divide ratio internally for NTC cold and NTC hot. In the ET9562, the I²C default setting is the PCB OTP. The function can be changed through the I²C (see [Table 1](#)).

I ² C Control		NTC PIN	Function
NTC_EN	PCB_OTP_EN		
0	X	Not Floating	Disable
1	0		NTC
1	1		PCB OTP
X	X	Floating	Disable

Table 1. NTC Function Selection Table

When PCB OTP is selected, if the NTC voltage is lower than the NTC hot threshold, both the LDO MOSFET and battery MOSFET are off. The PCB OTP fault sets the NTCH_FAULT status (Reg08 bit [1]) to 1 to indicate the fault. Operation resumes once the NTC voltage is higher than the NTC hot threshold.

The NTC function only works in charge mode. Once the NTC voltage falls out of the divide ratio (the temperature is outside the safe operating range), the IC stops the charging and reports it on the status bits. Charging resumes automatically after the temperature falls back into the safe range.

When NTC Pin is floating, NTC and PCB OTP function are disabled.

Safety Timer

The IC provides both a pre-charge and a fast charge safety timer to prevent extended charging cycles due to abnormal battery conditions. The safety timer is one hour when the battery voltage is below $V_{\text{TRICKLE_CHAR_VSET}}$. The fast charge safety timer begins when the battery enters fast charging. The fast charge safety timer can be programmed through the I²C. The safety timer feature can be disabled via the I²C.

The following actions restart the safety timer:

- A new charge cycle is kicked in Reg01 bit[3] is written from 0 to 1 (charge enable)
- Reg05 bit [3] is written from 0 to 1 (safety timer enable)
- Reg01 bit [7] is written from 0 to 1 (software reset)

Host Mode and Default Mode

The IC is a host-controlled device. After the power-on reset, all registers are in the default settings.

Any write to the IC changes it to host mode. All charge parameters are programmable. If the watchdog timer (Reg05 bit [5:4]) is not disabled, the host must reset the watchdog timer regularly by writing 1 to the Reg01 bit [6] before the watchdog timer expires to keep the device in host mode. Once the watchdog timer expires, the IC returns to default mode. The watchdog timer limit can also be programmed or disabled by the host control. When there is VIN, the default state of the watchdog timer is on, and the value is set as 160s. When there is no VIN, the default state of the watchdog timer is suspended. (Figure 6) Also, if the Reg05 bit[7] set to 1, then watchdog timer can also work when there is only Battery and no VIN.

The operation can also be changed to default mode when one of the following conditions occur:

- Refresh input without battery
- Re-insert battery with no VIN
- Register reset Reg01 bit [7] is reset

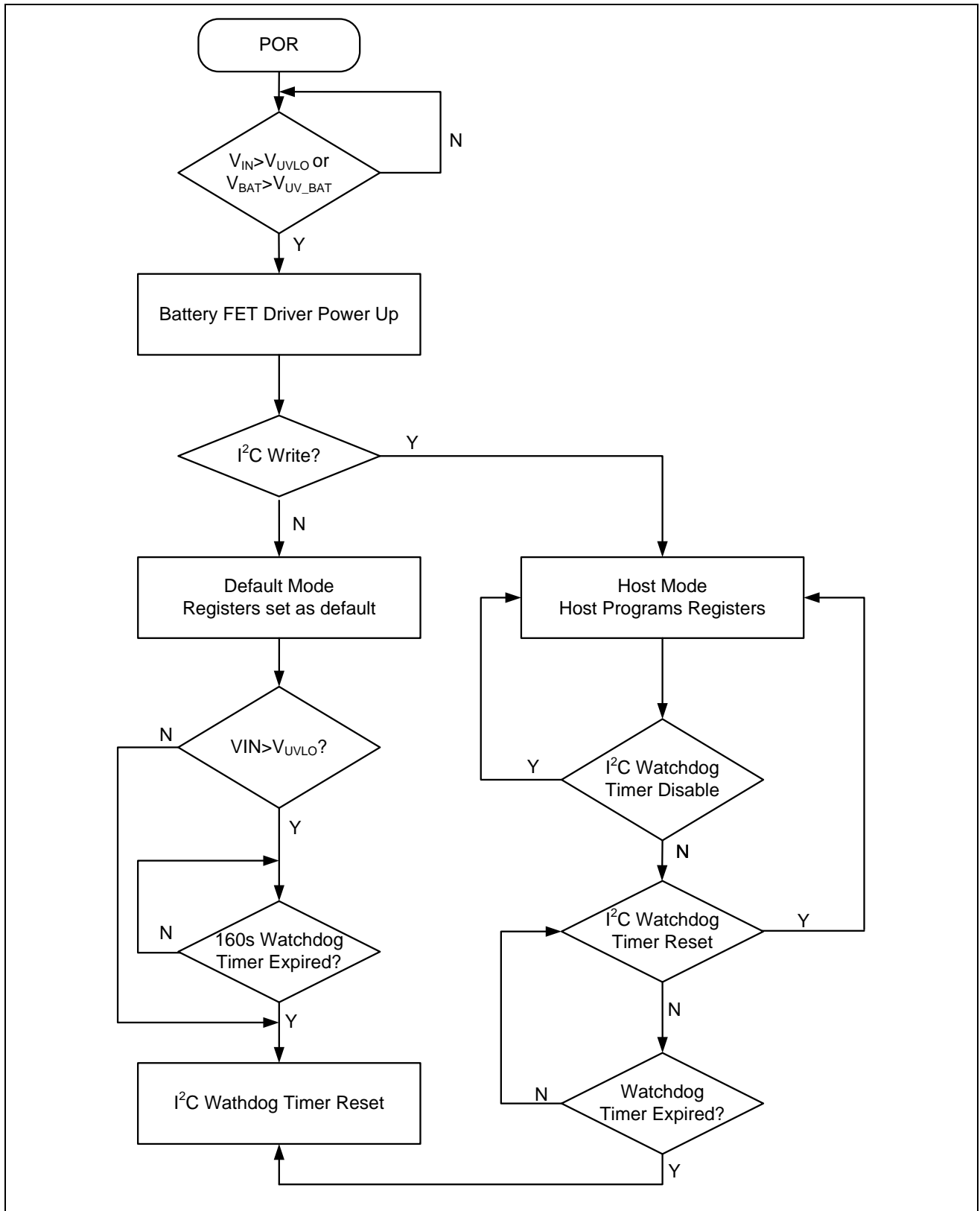


Figure 6. Default mode and Host mode Selection

Battery Discharge Function

If battery is connected and the input source is missing, the battery MOSFET is fully on when VBAT is above the V_{UV_BAT} threshold. The 100mΩ battery MOSFET minimizes conduction loss during discharge. The quiescent current of the IC is as low as 11μA in this mode. The low on resistance and low quiescent current help extend the running time of the battery.

Over-Discharge Current Protection

The IC has an over-discharge current protection in discharge mode and supplement mode. Once I_{BAT} exceeds the programmable discharge current limit (default 2A), the battery MOSFET is turned off after a 60μs delay, and the ET9562 enters hiccup mode in over-current protection. The discharge current can be programmed high to 2.67A through the I²C. If the discharge current goes high to reach the internal fixed current limit (about 3.7A), the battery MOSFET is turned off and starts hiccup mode immediately. The interval of the hiccup mode is 800μs.

Similarly, when the battery voltage falls below the programmable V_{UV_BAT} threshold (default 2.8V), the battery MOSFET is turned off to prevent over-discharge.

System Short-Circuit Protection (SCP)

The ET9562 features SYS node short-circuit protection (SCP) for the IN to SYS path and the BAT to SYS path.

The system voltage is continuously monitored. If V_{SYS} is lower than 1.5V, the system (SCP) for the IN to SYS path and the BAT to SYS path are active. I_{BATOC} is decreased to half of the original value.

1) IN to SYS path: Once I_{IN} is over the 360mA protection threshold, both the LDO MOSFET and the BAT MOSFET are turned off immediately, and the IC enters hiccup mode. Otherwise, the max current limit (360mA) are not reached and the setting input current limit are reached, and I_{IN} is regulated at IN_ILMTI_SET . Hiccup mode also starts after a 60μs delay. The interval of the hiccup mode is 800μs.

2) BAT to SYS path: Once I_{BAT} is over the 3.7A protection threshold, both the LDO MOSFET and the BAT MOSFET are turned off immediately, and the IC enters hiccup mode. When the battery discharge current limit threshold is reached, hiccup mode starts after a 60μs delay. The interval of the hiccup mode is 800μs.

If a system short-circuit occurs when both the input and battery are present, the protection mechanism of both paths work, with the faster one dominating the hiccup operation. ([Figure 7](#))

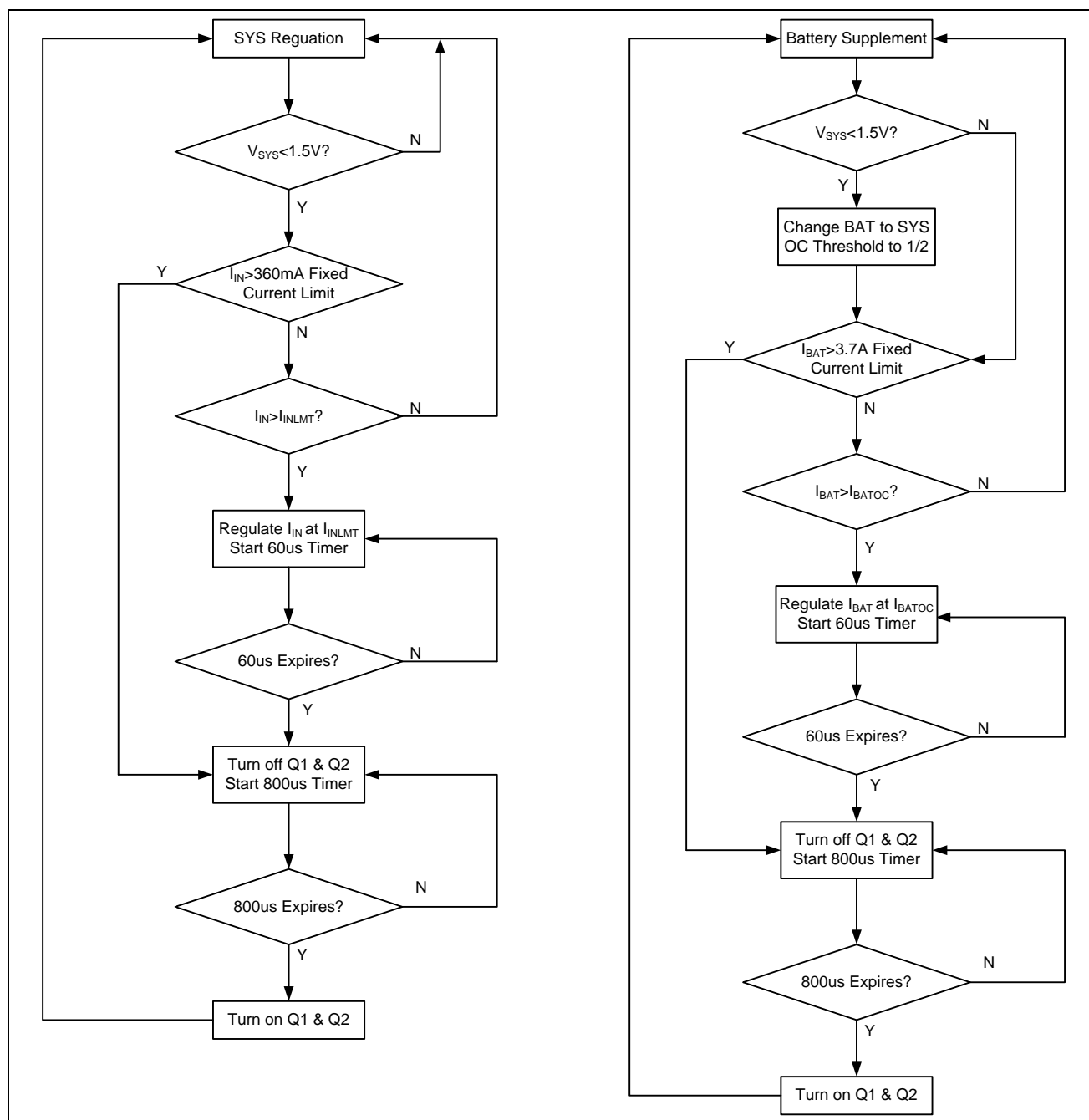


Figure 7. System Short-Circuit Protection

Interrupt to Host (INT)

The IC has an alert mechanism which can output an interrupt signal via INT to notify the system of the operation by outputting a 256μs low-state INT pulse. All of below events can trigger the INT output:

- Input Good Source detected
- UVLO or OVP for IN Port or $V_{IN} < V_{BAT} + 200\text{mV}$
- Charge Completed
- Any faults in Reg08(Watchdog time fault, Input fault, Thermal fault, Battery OVP fault, Safety time fault, NTC fault)

When any fault occurs, the IC sends out an INT pulse and latches the fault state in Reg08. After the IC exits the fault state, the fault bit could be released to 0 after the host reads Reg08. So the Reg08 register is not a real-time monitoring, if we want to get the chip's real-time working status, we should read the Reg08 for twice, and the data read the second time is the real-time working status of the chip.

The NTC fault is not latched and always reports the current thermistor conditions.

Note that the INT needs the external pull up resistor for its open-drain connection. Suggest the resistance not lower than 100kΩ.

If we set Reg0A[5]=0, the INT interrupt output will be closed.

Battery Disconnection Function

In applications where the battery is not removable, it is essential to disconnect the battery from the system:

Case A: to prevent excessive capacity discharge during the device is in shipping or storage.

Case B: allow the system power reset

The ET9562 provides both shipping mode and system reset mode for different application requirements.

1). Shipping Mode:

Entering the Shipping mode: The register bit (BATFET_EN), Reg06 Bit[5], controls the IC to enter the shipping mode.

During the normal operation, the battery MOSFET is turned on and this bit is 0. If this bit is set to 1 through I²C, the battery MOSFET is turned off, and the ET9562 enters shipping mode. The BATFET_EN bit is reset to 0 automatically after the battery MOSFET is turned off(refer to Figure 8).

When VIN is in place, we enter the shipping mode, the SYS will not be closed, and the chip will enter the shipping mode after the VIN removed.

Before entering the shipping mode, we pull down the INT, the shipping mode instruction should be input after INT wake up time(50ms/2s), or it will not enter the shipping mode. When we enter the shipping mode in this condition, the internal clock is waked up by the low INT, the current of BAT will be higher.

Exiting shipping mode: The IC can exit the shipping mode by pulling INT down or a valid VIN power on.

1.1) When the IC is in the shipping mode and only the Battery is present, pulling INT down by pushing KEY1 (see the "TYPICAL APPLICATION CIRCUIT") could wake the ET9562 up from shipping mode. (refer to [Table 2](#) and [Figure 8](#))

If we set Reg0A[4]=0, the INT exiting shipping mode and SYS reset function will be closed.

	INT Signal	IC Exits the Shipping Mode
Case1(int_exit_ship_tset=0), Reg0A Bit1	One negedge of INT and INT Keep Low level>50ms	At Once
Case2(int_exit_ship_tset=1), Reg0A Bit1	One negedge of INT and INT Keep Low level >2s	At Once

Table 2. Exit Shipping mode with BAT present only

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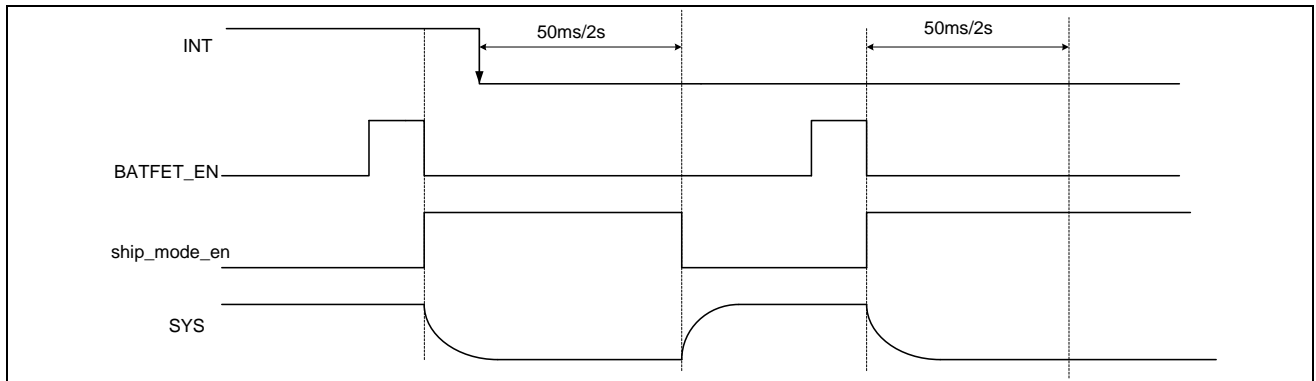


Figure 8. Enter Shipping mode and Exit Shipping mode by INT Low Level

1.2) When the IC is in the shipping mode and a valid VIN powers on, the ET9562 could be woken up too. After effective VIN voltage is preset, the ET9562 could be woken up from the shipping mode by the IN Power Good signal(refer to [Table 3](#) and [Figure 9](#)).

VIN voltage effective condition:

- $V_{IN} > V_{IN_UVP}$
- $V_{IN} < V_{IN_OVP}$
- $V_{IN} > V_{BAT} + 200mV$

	IN Signal(Power Good Signal)	IC Exists the Shipping Mode
Case1(in_exit_ship_tset=0), Reg0A Bit0	One posedge of IN Power Good and Keep Power Good Signal>50ms	At Once
Case2(in_exit_ship_tset=1), Reg0A Bit0	One posedge of IN Power Good and IN Keep Power Good Signal >2s	At Once

Table 3. Exit Shipping mode with VIN powers on

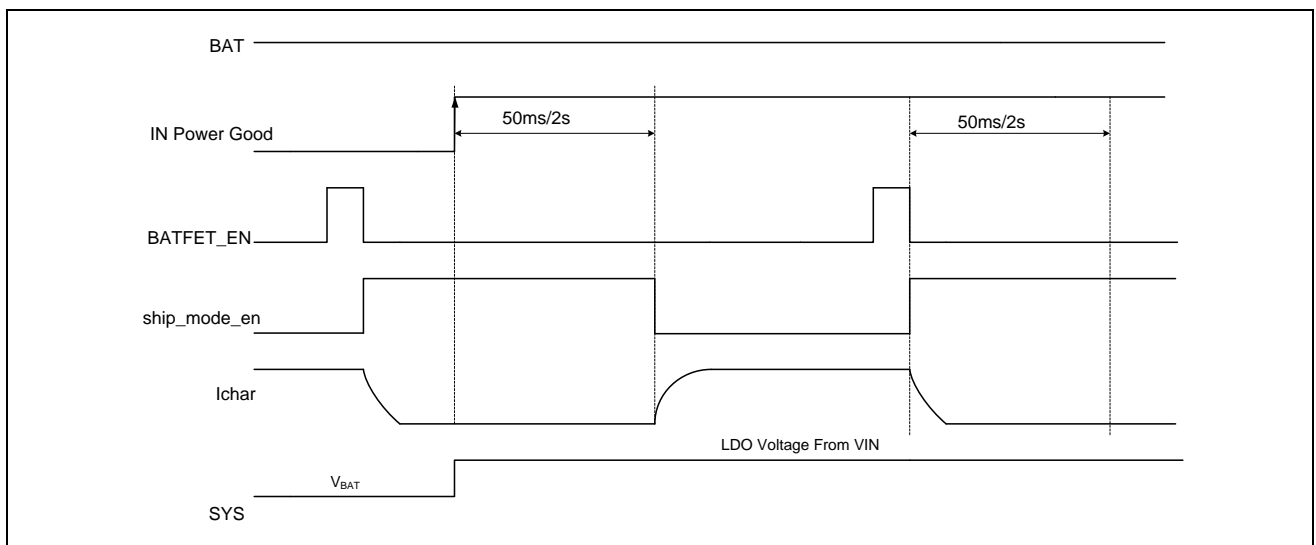


Figure 9. Enter Shipping mode and Exit Shipping mode by IN Good Signal

2). Reset Mode

The IC can use INT or Watchdog Overflow Signal to cut off the path from the IN to the system and battery to the system when system reset is needed.

Once the logic at INT is set to low for more than 8s/16s(Reg0A bit3) or watchdog time is overflow, the battery is disconnected from the system by turning off the LDO MOSFET and the battery MOSFET. At the same time SYS will be discharged by internal discharge circuit.

If we set Reg0A[4]=0, the INT exiting shipping mode and SYS reset function will be closed.

The off state lasts for 2s/4s(Reg0A bit2) for INT(keep low for more than 8s/16s), and only 4s for Watchdog Overflow Signal, then the LDO MOSFET and the battery MOSFET are turned on automatically, and the system is powered again. During the 2s/4s off period, INT pin voltage level could be high or low. The IC can reset the system by controlling INT (see [Figure 10](#)).

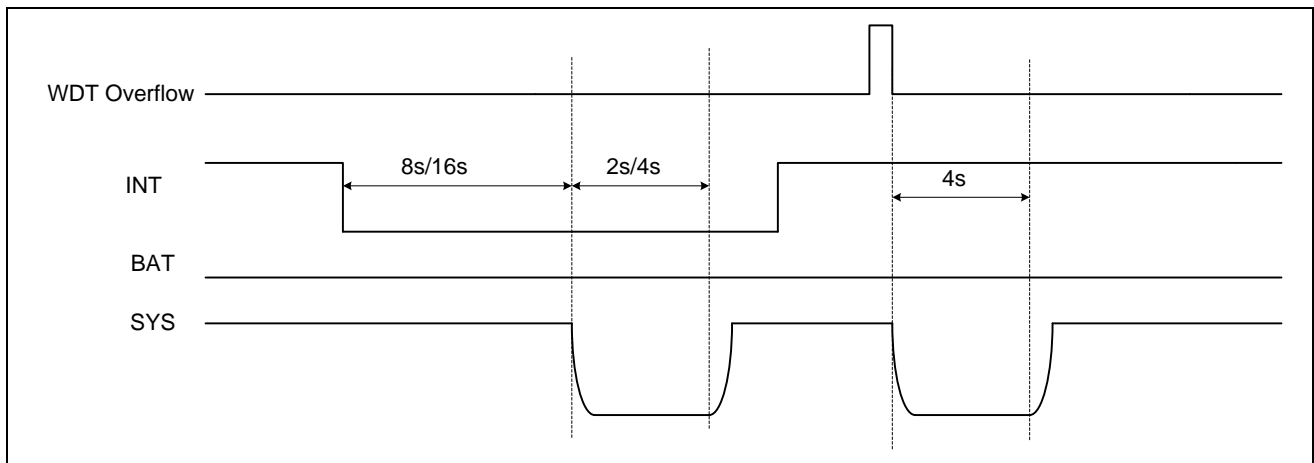


Figure 10. System Reset Function Operation Profile

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I²C REGISTER MAP

Chip Address: 1001000b (7bit) = 48H

NOTE: 10010000b (8bit) = 90H(Writing Register mode)/10010001 (8bit) =91H(Reading Register Mode)

Input Source Control Register/Address: 00H (Default: 1001 1111b)

Bit	Symbol	Description	Read/Write	Default
Input Voltage Regulation				
Bit 7	IN_VSET[3]	1b: 640mV	Read/write	Offset: 3.88V Range:3.88V-5.08V Default:4.60V(1001b)
Bit 6	IN_VSET[2]	1b: 320mV		
Bit 5	IN_VSET [1]	1b: 160mV		
Bit 4	IN_VSET [0]	1b: 80mV		
Input Current Limit				
Bit 3	IN_ILIMIT_SET[3]	1b: 320mA	Read/write	Offset: 80mA Range: 80mA-680mA Default:680mA(1111b)
Bit 2	IN_ILIMIT_SET[2]	1b: 160 mA		
Bit 1	IN_ILIMIT_SET[1]	1b: 80 mA		
Bit 0	IN_ILIMIT_SET[0]	1b: 40 mA		

Power-On Configuration Register/Address: 01H (Default: 0010 0100b)

Bit	Symbol	Description	Read/Write	Default
Bit 7	REG_RST	0b: keep current setting 1b: reset all the register	Read/write	Keep current setting(0b)
Bit 6	WDT_RST	0b: normal 1b: reset watchdog timer	Read/write	Normal(0b)
Bit 5	LDO_EN ⁽¹⁾	0b: disable LDO 1b: enable LDO	Read/write	enable(1b)
Bit 4	LDO_MODE_SEL	0b: LDO mode 1b: Switch mode	Read/write	LDO mode(0b)
Charger Configuration				
Bit 3	CHAR_EN	0b: charge disabled 1b: charge enabled	Read/write	Charge Disabled (0b)
Battery UVLO Threshold				
Bit 2	BAT_UVLO_SET[2]	1b: 0.4V	Read/write	Offset: 2.4V Range: 2.4V-3.1V Default: 2.8V (100b)
Bit 1	BAT_UVLO_SET[1]	1b: 0.2V		
Bit 0	BAT_UVLO_SET[0]	1b: 0.1V		

Note1. This bit only controls the on and off of the LDO MOSFET.

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Charge Current Control Register/Address: 02H (Default: 0001 1110b)

Bit	Symbol	Description	Read/Write	Default
Bit 7	Reserved		Read/write	Reserved
Bit 6	Reserved		Read/write	Reserved
Charge Current Setting				
Bit 5	CHAR_ISET [5]	1b: 256mA	Read/write	Offset: 8mA Range: 8mA -512mA Default:248mA(011110)
Bit 4	CHAR_ISET [4]	1b: 128mA		
Bit 3	CHAR_ISET [3]	1b: 64mA		
Bit 2	CHAR_ISET [2]	1b: 32mA		
Bit 1	CHAR_ISET [1]	1b: 16mA		
Bit 0	CHAR_ISET [0]	1b: 8mA		

Discharge Current Limit/Address: 03H (Default: 0001 0011b)

Bit	Symbol	Description	Read/Write	Default
Bit 7	Reserved		Read/write	Reserved
Bit 6	Reserved		Read/write	Reserved
Bit 5	Reserved		Read/write	Reserved
BAT to SYS Discharge Current Limit (Note: Bit[4:0] can be set 11010~11111 and clamp to 2.67A)				
Bit 4	BATTOSYS_ISET [4]	1b: 1600mA	Read/write	Offset: 170mA Range: 170mA~2.67A Valid range: 00001b ~11001b Default: 2070mA(10011b)
Bit 3	BATTOSYS_ISET [3]	1b: 800mA		
Bit 2	BATTOSYS_ISET [2]	1b: 400mA		
Bit 1	BATTOSYS_ISET [1]	1b: 200mA		
Bit 0	BATTOSYS_ISET [0]	1b: 100mA		

Charge Voltage Control Register/Address: 04H (Default: 1010 0011b)

Bit	Symbol	Description	Read/Write	Default
Battery Regulation Voltage				
Bit 7	BATREG_VSET[5]	1b: 480mV	Read/write	Offset: 3.60V Range: 3.60V~4.545V Default: 4.2V (101000b)
Bit 6	BATREG_VSET[4]	1b: 240mV		
Bit 5	BATREG_VSET[3]	1b: 120mV		
Bit 4	BATREG_VSET[2]	1b: 60mV		
Bit 3	BATREG_VSET[1]	1b: 30mV		
Bit 2	BATREG_VSET[0]	1b: 15mV		
Trickle Charge Threshold				
Bit 1	TRICKLE_CHAR_VSET	0b: 2.8V 1b: 3.0V	Read/write	3.0V (1b)
Battery Recharge Threshold (below BATREG_VSET)				
Bit 0	BAT_RCHAR_VSET	0b: 100mV 1b: 200mV	Read/write	200mV (1b)

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Charge Termination/Timer Control Register/Address: 05H (Default: 0111 1010b)

Bit	Symbol	Description	Read/Write	Default
Bit 7	WDT_WKMD	0b: Watchdog Timer can only work in charge state 1b: Watchdog Timer can work in charge and discharge state	Read/write	Work in charge state(0b)
Termination Setting (the termination is allowed or not)				
Bit 6	BF_EN	0b: disable 1b: enable	Read/write	Enabled(1b)
I ² C Watchdog Timer Limit				
Bit 5	WDT_TSET[1]	00b: disable timer 01b: 40s 10b: 80s 11b: 160s	Read/write	Enable timer(11b)
Bit 4	WDT_TSET[0]			
Safety Timer Setting				
Bit 3	SAFET_EN	0b: disable 1b: enable	Read/write	Enable timer (1b)
Constant Current Charge Timer				
Bit 2	CONSC_TSET[1]	00b: 3hrs 01b: 5hrs 10b: 8hrs 11b: 12hrs	Read/write	5hrs (01b)
Bit 1	CONSC_TSET[0]			
Termination Timer Control (when TERMI_TEN is enabled, the IC will not suspend the charge current after charge termination)				
Bit 0	TERMI_TEN	0b: disable 1b: enable	Read/write	Disable(0b)

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Miscellaneous Operation Control Register/Address: 06H (Default: 0100 1111b)

Bit	Symbol	Description	Read/Write	Default
Bit 7	Reserved		Read/write	Read/write
Bit 6	SAFET_2X_EN	0b: disable 2X extended safety timer during PPM 1b: enable 2X extended safety timer during PPM	Read/write	Enable (1b)
Bit 5	BATFET_EN ⁽²⁾	0b: enable 1b: turn off	Read/write	Enable(0b)
Bit 4	Reserved	-	Read only	Reserved
Bit 3	NTC_EN	0b: disable 1b: enable	Read/write	Enable(1b)
Bit 2	PCB_OTP_EN	0b: disable 1b: enable	Read/write	Enable(1b)
Thermal Regulation Threshold				
Bit 1	THERMALT_SET[1]	00b: 60°C 01b: 80°C 10b: 100°C 11b: 120°C	Read/write	120°C (11b)
Bit 0	THERMALT_SET[0]			

Note2. This bit controls the on and off of the battery MOSFET, including the charging and discharging.

System Status Register/Address: 07H (Default: 0000 0000b)

Bit	Symbol	Description	Read/Write	Default
Bit 7	Reserved	-	Read only	Reserved
Revision				
Bit 6	Reserved	-	Read only	Reserved
Bit 5	Reserved			
Bit 4	CHAR_STATUS [1]	00b: not charging 01b: trickle charge 10b: charge 11b: charge done	Read only	Not charging (00b)
Bit 3	CHAR_STATUS [0]			
Bit 2	PPM_EN	0b: no PPM 1b: In PPM	Read only	No PPM (0b) (no power-path management happens)
Bit 1	IN_POWER_GOOD	0b: in power good 1b: in power fail	Read only	In power good (0b)
Bit 0	THERM_STR	0b: no thermal regulation 1b: in thermal regulation	Read only	Normal (0b)

Note3. The 07H register is a real-time monitoring and the fault state is not latched.

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Fault Register/Address: 08H (Default: 0000 0000)

Bit	Symbol	Description	Read/Write	Default
Bit 7	Reserved		Read only	Reserved
Bit 6	WDT_FAULT	0b: normal 1b: watchdog timer expiration	Read only	Normal (0b)
Bit 5	VIN_FAULT	0b: normal 1b: input fault (OVP or UVP of IN Voltage)	Read only	Normal (0b)
Bit 4	THEM_SD	0b: normal 1b: thermal shutdown	Read only	Normal (0b)
Bit 3	BAT_FAULT	0b: normal 1b: battery OVP	Read only	Normal (0b)
Bit 2	SAFET_FAULT	0b: normal 1b: safety timer expiration	Read only	Normal (0b)
Bit 1	NTCH_FAULT	0b: normal 1b: NTC hot	Read only	Normal (0b)
Bit 0	NTCL_FAULT	0b: normal 1b: NTC cold	Read only	Normal (0b)

Note4.WDT_FAULT is cleared after the Reg01[6]=1 and the host should read the Reg08.

VIN_FAULT、THEM_SD、BAT_FAULT、SAFET_FAULT are cleared after the host reads the Reg08

NTC_FAULT is not latched and always reports the current thermistor conditions.

System output voltage / Pre-Charge/Termination Current /Address: 09H (Default: 0011 1001b)

Bit	Symbol	Description	Read/Write	Default
Bit 7	Reserved		Read only	Reserved
System Output Voltage Regulation				
Bit 6	SYS_VSET[3]	1b: 400mV	Read/write	Offset: 4.25V Range: 4.25V-5.0V Default: 4.6V (0111b)
Bit 5	SYS_VSET[2]	1b: 200mV		
Bit 4	SYS_VSET[1]	1b: 100mV		
Bit 3	SYS_VSET[0]	1b: 50mV		
Trickle Current /termination current (Note: Bit[2:0] can not be set to 010 when CHAR_ISET ≥ 264mA)				
Bit 2	TRICKLE_CHAR_ISET[2]	000b: 1mA 001b: 2mA 010b: 4mA	Read/write	Range: 1mA-34mA Default: 2mA (001b)
Bit 1	TRICKLE_CHAR_ISET[1]	011b: 10mA 100b: 16mA		
Bit 0	TRICKLE_CHAR_ISET[0]	101b: 22mA 110b: 28mA 111b: 34mA		

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Debounce Time for SYS Reset and Exit Shipmode /Address: 0AH (Default: 0011 1110)

Bit	Symbol	Description	Read/Write	Default
Bit 7	Reserved			Reserved
Bit 6	Reserved			Reserved
Bit 5	INT_OUTEN	INT Port Output Function Enable Signal(low level to mask all interrupt output function) 0b: Disable 1b:Enable	Read/write	Enable(1b)
Bit 4	INT_ILOW_FUN_EN	INT Port Input Low Level Function Enable Signal(low level to mask INT Port Exiting Shipping mode and Producing SYS Reset) 0b: Disable 1b: Enable	Read/write	Enable(1b)
Bit 3	INT_RESET_TSET	INT Port Low Level Time Setting for Producing Reset Signal in SYS Port 0b:8s 1b:16s	Read/write	16s(1b)
Bit 2	SYS_RESET_TSET	SYS Port Keeping Low Reset Level Time Setting when Watchdog Overflow or INT Port Keep 8/16s Low Level 0b:2s 1b:4s	Read/write	4s(1b)
Bit 1	INT_EXIT_SHIP_TSET	INT Port Low Level Time Setting for Exit Shipping mode 0b:50ms 1b:2s	Read/write	2s(1b)
Bit 0	IN_EXIT_SHIP_TSET	IN Port Power Good Time Setting for Exit Shipping mode 0b:50ms 1b:2s	Read/write	50ms(0b)

Serial Port Interface (I²C)

Bus Interface

Baseband Processor can transmit data with ET9562 each other through SDA and SCL port. SDA and SCL composite bus interface, and a pull-up resistor to the power supply should be connected.

Data Validity

When the SCL signal is HIGH, the data of SDA port is valid and stable. Only when the SCL signal is low, the level on the SDA port can be changed.

Start (Re-start) and Stop Working Conditions

When the SCL signal is high, SDA signal from high to low represents start or re-start working conditions, while the SCL signal is high, SDA signal from low to high represents stop working conditions.

Byte format

Each byte of data line contains 8 bits, which contains an acknowledge bit. The first data is transmitted MSB.

Acknowledge

During the writing mode, ET9562 will send a low level response signal with one period width to the SDA port. During the reading mode, ET9562 will not send response signal and the host will send a high response signal one period width to the SDA.

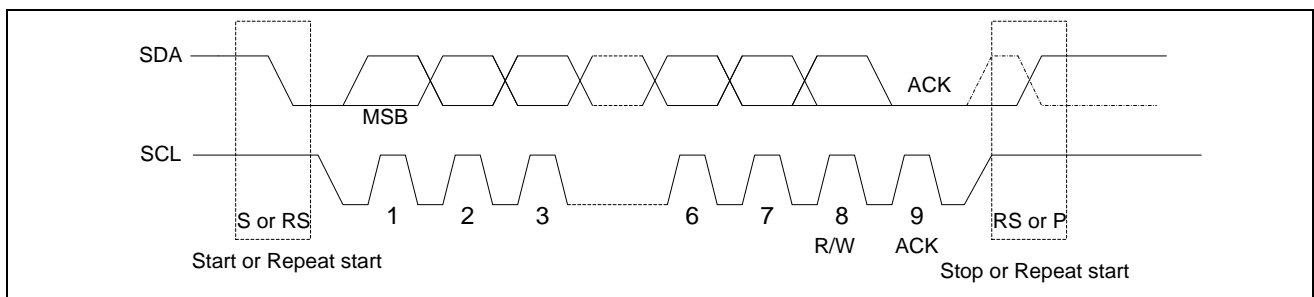


Figure 11. I²C write mode

- ACK=Acknowledge
- MSB=Most Significant Bit
- S=Start Conditions
- RS=Restart Conditions
- P=Stop Conditions
- Fastest Transmission Speed =400KBITS/S
- Restart: SDA-level turnover as expressed by the dashed line waveform

Chip Address: 10010000b(Writing Register mode) / 10010001b(Reading Register Mode)

I²C Writing Command Register Interface Protocol (continuous):

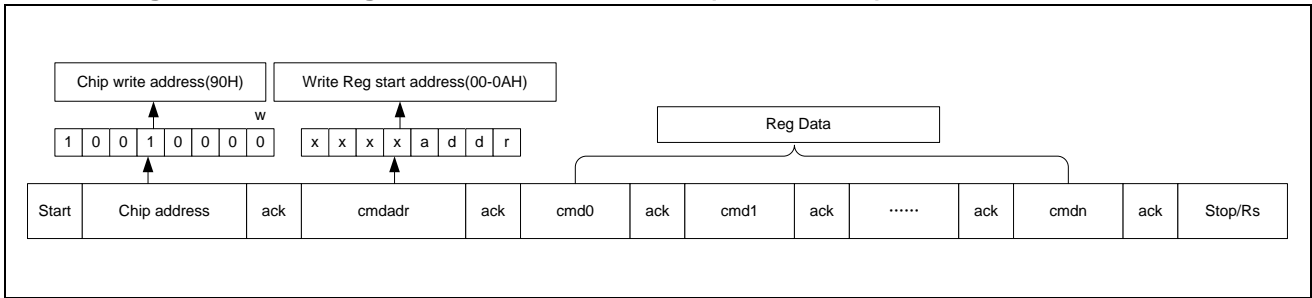


Figure 12. I²C Writing Command Register(continuous)

- Start=Start Conditions
- Chip address=Write register address =1001000+0(w)b
- ack=Acknowledge
- Write Reg start address byte = cmdadr(xxxx + REG's 4bit addr)
- ack=Acknowledge
- Reg data 0 = cmd0(Command data0)
- ack=Acknowledge
-
- Reg data n =cmdn(Command datan)
- ack=Acknowledge
- Stop/Rs=Stop Condition/Restart Condition

I²C Writing Command Register Interface Protocol (single):

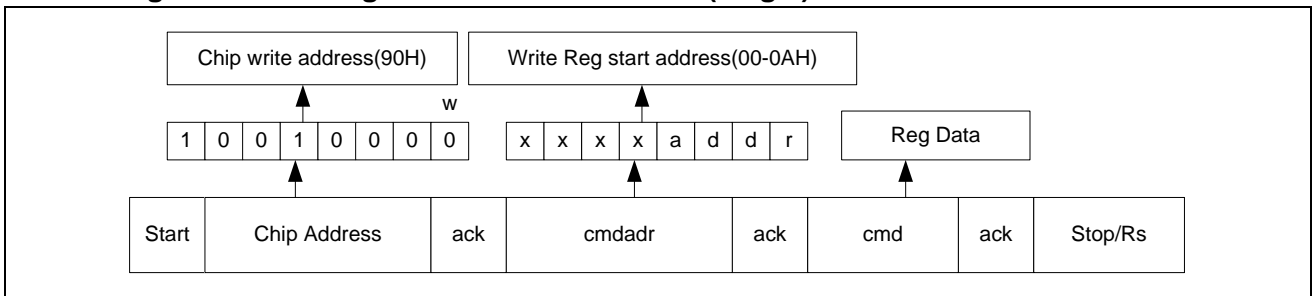


Figure 13. I²C Writing Command Register(single)

- Start=Start Conditions
- Chip address =Write register address=1001000+0(w)b
- ack=Acknowledge
- Write Reg start address byte = cmdadr(xxxx + REG's 4bit addr)
- ack=Acknowledge
- Reg data= cmd(Command data)
- ack=Acknowledge
- Stop/Rs=Stop Condition/Restart Condition

I²C Reading Command Register Interface Protocol:

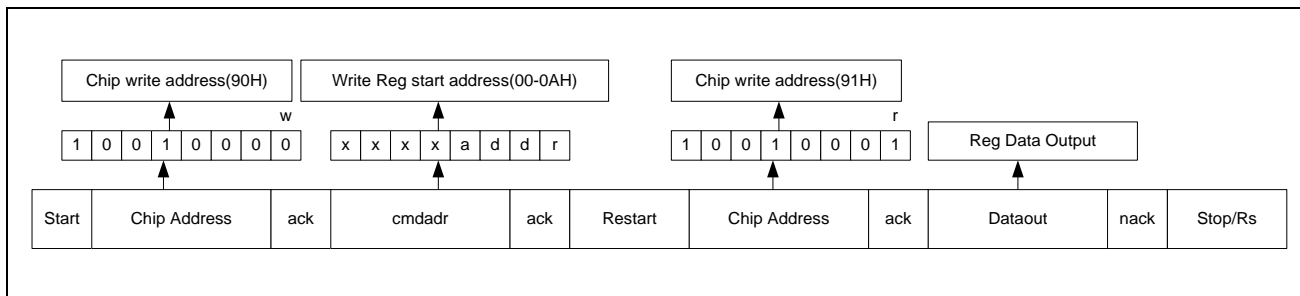


Figure 14. I²C Reading Command Register

- Start=Start Conditions
- Chip address =Write register address=1001000+0(w)b
- ack=Acknowledge
- Write Reg start address byte = cmdadr(xxxx + REG's 4bit addr)
- ack=Acknowledge
- Restart=Restart condition
- Chip address Read register address=1001000+1(r)b
- ack=Acknowledge
- Dataout=Register data output
- nack=No Acknowledge
- Stop/Rs=Stop Condition/Restart Condition

Absolute Maximum Ratings

Stresses exceeding the absolute maximum ratings may damage the device. The device may not function or be operable above the recommended operating conditions and stressing the parts to these levels is not recommended. In addition, extended exposure to stresses above the recommended operating conditions may affect device reliability. The absolute maximum ratings are stress ratings only.

Characteristic		Range		Unit
VIN, Supply Input Voltage		-0.3~24		V
Other Pins		-0.3~6.0		V
Maximum Continuous Current of IN to BAT		<1.0		A
Maximum Continuous Current of IN to SYS		<1.5		A
Maximum Continuous Current of BAT to SYS		<3.0		A
Power Dissipation at T _A = +70°C		<1.5		W
Storage Junction Temperature		-60~150		°C
Thermal Resistance		55		°C /W
Operating Temperature Range		-40~85		°C
Soldering Temperature (reflow)		<+260		°C
Junction Temperature		<+150		°C
Electrostatic Discharge Capability	Human Body Model	All Pins	>2.0	kV
	Charged Device Model	All Pins	>1.0	kV

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Electrical Characteristics

Unless otherwise noted, typical values are at $V_{IN}=5V$, $V_{BAT}=4V$, $T_A=25^{\circ}C$.

Symbol	Parameters	Conditions	Min	Typ	Max	Unit
Power Supply						
V_{IN}	Input voltage				20	V
V_{IN}	Input operation voltage		4.35	5	5.5	V
I_{IN1}	Supply current at IN, charge enable	$V_{IN}=5.5V$, $I_{CHG}=0A$, $I_{SYS}=0A$, charge enable, $BAT=4.3V$		550	700	μA
I_{IN2}	Supply current at IN, charge disable	$V_{IN}=5.5V$, $I_{CHG}=0A$, $I_{SYS}=0A$, charge disable, $BAT=4.3V$		450	600	μA
I_{IN3}	Supply current at IN, LDO disable	$V_{IN}=5.5V$, $I_{CHG}=0A$, $I_{SYS}=0A$, LDO disable, $BAT=4.3V$		350	500	μA
I_{BAT}	Supply current at BAT	$V_{IN}=0V$, $I_{SYS}=0A$, $V_{BAT}=4.35V$, disable PCB OTP function, do not include the current from external NTC resistor		15	18	μA
		$V_{IN}=0V$, $I_{SYS}=0A$, $V_{BAT}=4.35V$, enable PCB OTP function, do not include the current from external NTC resistor, watchdog is not available in discharge mode		22	25	μA
		$V_{IN}=0V$, $I_{SYS}=0A$, $V_{BAT}=4.35V$, enable PCB OTP function, do not include the current from external NTC resistor, watchdog is available in discharge mode		25	30	μA
		$V_{SYS}=V_{IN}=0V$, $I_{SYS}=0A$, $V_{BAT}=4.35V$, Set disconnect mode.		1.5	2	μA
V_{IN_OVP}	Input over-voltage protect threshold	Input rising threshold	5.85	6.0	6.15	V
	OVP threshold hysteresis	Input Voltage Falling		350		mV
V_{UV_IN}	Input under-voltage threshold	Input rising threshold	3.8	3.9	4.0	V
	Input UVLO hysteresis			170		mV

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Electrical Characteristics(Continued)

Unless otherwise noted, typical values are at $V_{IN}=5V$, $V_{BAT}=4V$, $T_A=25^{\circ}C$.

Symbol	Parameters	Conditions	Min	Typ	Max	Unit
V _{UV_BAT}	Battery under-voltage threshold	Battery voltage falling. Reg01[2:0]=100b	2.6	2.8	3.0	V
	Battery UVLO range		2.4		3.1	V
	Battery UVLO hysteresis			210		mV
V _{BAT_OVP}	Battery over-voltage protect threshold	Battery voltage rising, higher than V _{BATREG_VSET}		130		mV
		Battery voltage falling, higher than V _{BATREG_VSET}		70		mV
Power Path Management						
V _{SYS_REG}	Regulated system output voltage	V _{IN} =5.5V, I _{SYS} =10mA, I _{CHG} =0A Reg09[6:3]=0111b, default	4.50	4.60	4.70	V
	System output voltage range		4.25		5.0	V
I _{IN_LIM}	Input current limit	Default Reg00[3:0]=1111b	600	640	680	mA
	Input current limit range		80		680	mA
V _{IN_REG}	Input voltage regulation threshold	Default Reg00[7:4]=1001b	4.45	4.60	4.75	V
	Input voltage regulation range		3.88		5.08	V
V _{SYS}	System output voltage	Charging mode, V _{IN} =5.5V, V _{BAT} =3.7V, default Reg09[6:3]=0111b	4.50	4.60	4.70	V
		Battery supply mode, V _{BAT} =3.7V, I _{BAT} =100mA	3.6			V
		V _{IN} <V _{UV_IN} and V _{BAT} <V _{UV_BAT}		0		V
R _{ON_SYS}	IN to SYS switch on resistance	V _{SYS} =4.6V, I _{SYS} =100mA		150	250	mΩ
R _{ON_BAT}	BAT to SYS switch on resistance	V _{IN} <2V, V _{BAT} =3.5V, I _{SYS} =100mA		100	150	mΩ
I _{BAT_MAX}	BAT to SYS current limit	Reg03[4:0]=10011b	1770	2070 ⁽⁵⁾	2370	mA
	BAT to SYS current limit range		170		2670 ⁽⁵⁾	mA
I _{BAT_LEK}	BAT to SYS leakage current	V _{BAT} =4.5V, V _{IN} =V _{SYS} =0V, Disconnect mode.			1	uA

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Electrical Characteristics(Continued)

Unless otherwise noted, typical values are at $V_{IN}=5V$, $V_{BAT}=4V$, $T_A=25^{\circ}C$.

Symbol	Parameters	Conditions	Min	Typ	Max	Unit
I _{SYS_LEK}	SYS to BAT leakage current	V _{SYS} =5.0V, V _{IN} =4.5V, V _{BAT} =0V			1	uA
T _{INT}	BAT discharge function controlled by INT	INT pull-low lasting time to turn off the battery discharge function		16		s
		Battery MOSFET lasts for the off time duration before auto-on		4		s
Battery Charger						
V _{BAT_REG}	Battery voltage regulation range	Programmed by I ² C V _{SYS_REG} >V _{BAT_REG} +200mV	3.600		4.545	V
V _{BAT}	Default battery regulation voltage	Reg04[7:2]=101000b	4.175	4.200	4.225	V
I _{CHG}	Battery charge current range	V _{IN} =5V, V _{BAT} =3.8V step=8mA	8		512	mA
	Default charge current	V _{IN} =5V, V _{BAT} =3.8V Reg02[5:0]=011110b	235	248	261	mA
	Charge current	V _{IN} =5V, V _{BAT} =3.8V Reg02[5:0]=001010b	83	88	93	mA
		V _{IN} =5V, V _{BAT} =3.8V Reg02[5:0]=000000b	7	8	9	mA
	Charging current thermal foldback threshold	Junction Temperature Regulation Reg06[1:0]=11b		120 ⁽⁵⁾		°C
I _{TC}	Trickle current range	Programmed range Reg09H[2:0]	1		34	mA
I _{BF}	End of charge current threshold	I _{CHG} ≤256mA, I _{TC_SETTING} =2mA Reg02bit[5]=0b	1	2	3	mA
		I _{CHG} ≤256mA, I _{TC_SETTING} =22mA Reg02bit[5]=0b	18	22	26	mA
		I _{CHG} ≥264mA, I _{TC_SETTING} =2mA Reg02bit[5]=1b	2	4	6	mA
		I _{CHG} ≥264mA, I _{TC_SETTING} =22mA Reg02bit[5]=1b	39	44	49	mA
V _{BAT_LOW}	Trickle charge threshold voltage	V _{BAT} rising, set 3.0V	2.8	3.0	3.2	V
	Trickle voltage hysteresis			60		mV

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Electrical Characteristics(Continued)

Unless otherwise noted, typical values are at $V_{IN}=5V$, $V_{BAT}=4V$, $T_A=25^{\circ}C$.

Symbol	Parameters	Conditions	Min	Typ	Max	Unit
V _{RECHG}	Recharge threshold below V _{BAT_REG}	Reg04[0]=0b	70	100	130	mV
		Reg04[0]=1b	160	200	240	mV
Thermal Protection						
	Thermal shutdown rising threshold			150 ⁽⁵⁾		°C
	OTP Threshold Hysteresis			20 ⁽⁵⁾		°C
I _{NTC}	NTC output current	NTC=3.0V		500		nA
V _{COLD}	NTC cold temp rising threshold	As a percentage of V _{DD}	63	65	67	%
	NTC cold temp rising threshold hysteresis			60		mV
V _{HOT}	NTC hot temp falling threshold	As a percentage of V _{DD}	31	33	35	%
	NTC hot temp falling threshold hysteresis			70		mV
V _{HOT_PCB}	NTC hot temp falling threshold for PCB OTP	As a percentage of V _{DD}	30	32	34	%
	NTC hot temp falling threshold hysteresis for PCB OTP			85		mV
Logic I/O Characteristics						
V _{IL}	Low Logic voltage threshold				0.4	V
V _{IH}	High Logic voltage threshold		1.3			V
Digital Clock and Watchdog Timer						
F _{DIG}	Digital clock			32		kHz
t _{WDT}	Watchdog Timer	Reg05[5:4]=11b		160		s

Note5. Guaranteed by design and characterization. Not a FT item.

I²C mode Timing

Symbol	Parameters	Min	Typ	Max	Unit
F_{SCL}	SCL Clock Frequency	0	-	400	kHz
t_{BUF}	Bus Free Time Between a STOP and START Condition	1.3	-	-	μs
$t_{HD:STA}$	Hold Time(Repeated) START Condition	0.6	-	-	μs
t_{LOW}	Low Period of SCL Clock	1.3	-	-	μs
t_{HIGH}	HIGH Period of SCL Clock	0.6	-	-	μs
$t_{SU:STA}$	Setup Time for a Repeated START Condition	0.6	-	-	μs
$t_{HD:DAT}$	Data Hold Time	-	-	0.9	μs
$t_{SU:DAT}$	Data Setup Time	100	-	-	ns
t_R	Data Hold Time2	-	$20+0.1C_b^{(6)}$	300	ns
t_F	Data Hold Time2	-	$20+0.1C_b^{(6)}$	300	ns
$t_{SU:STO}$	Setup Time for STOP Condition	0.6	-	-	μs

Note6. C_b =total capacitance of one bus line in PF.

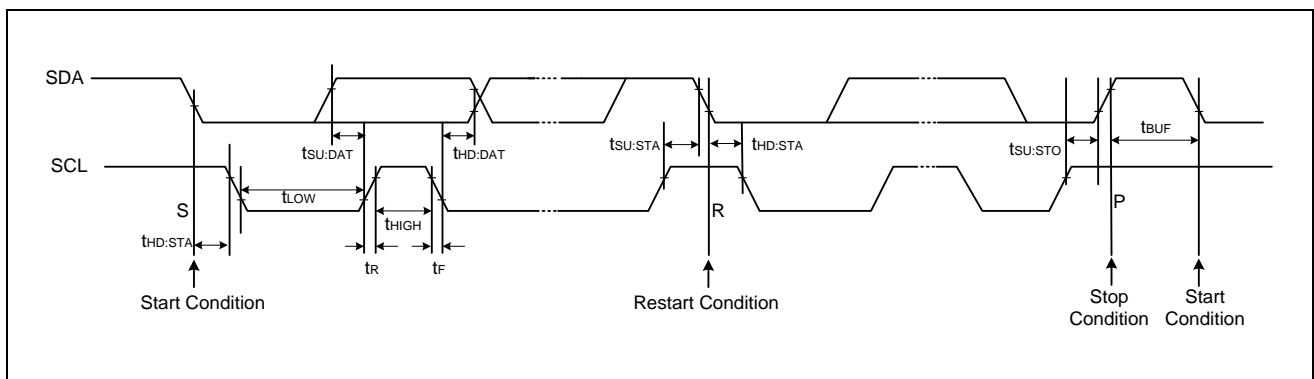
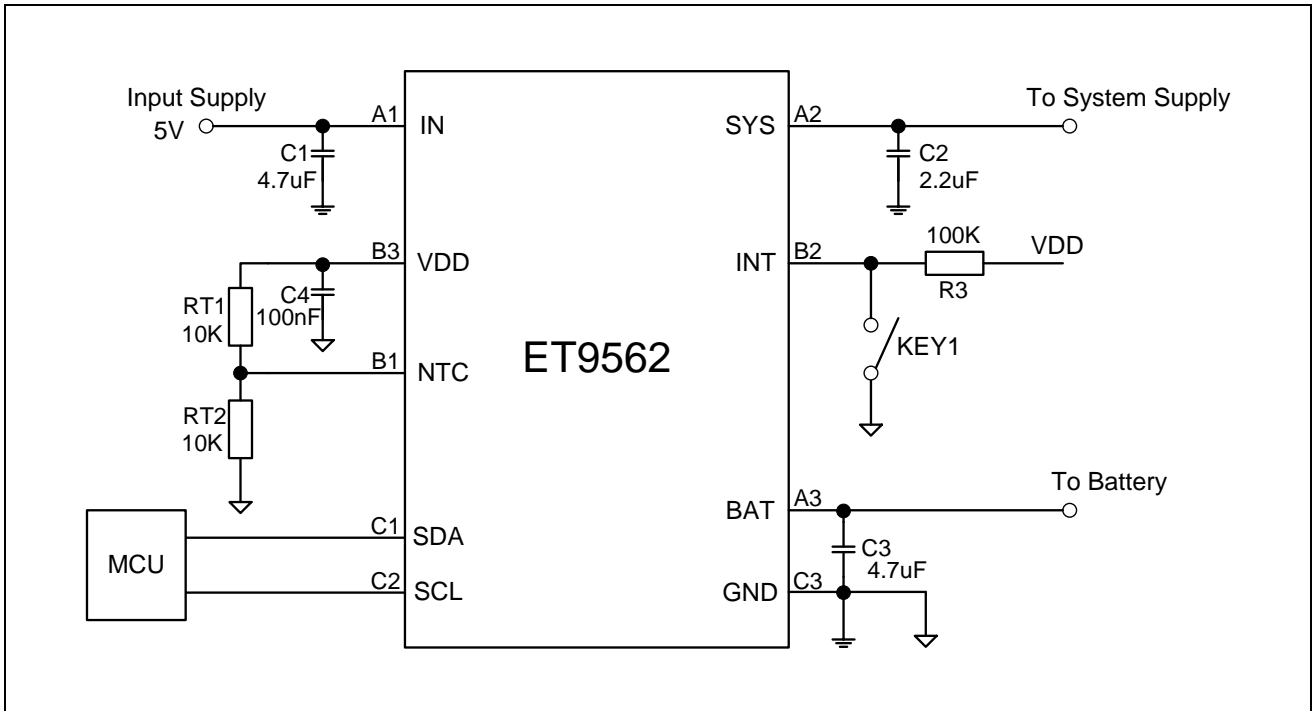


Figure 15. I²C mode Timing Diagram

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Typical Application Circuits

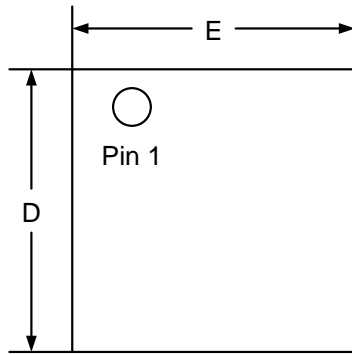


Note*. This electric circuit only supplies for reference.

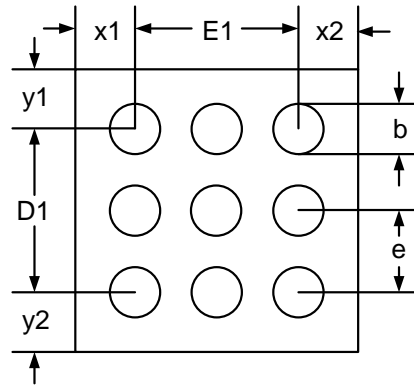
ET9562

Package Dimension

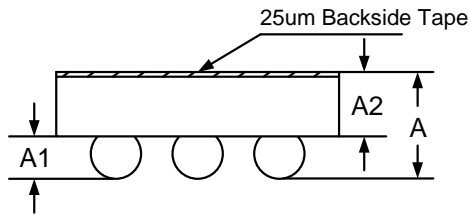
CSP9



TOP VIEW
(MARK SIDE)



BOTTEM VIEW
(BALL SIDE)



SIDE VIEW

COMMON DIMENSIONS
(UNITS OF MEASURE=MILLIMETER)

SYMBOL	MIN	NOM	MAX
A	0.580	0.625	0.670
A1	0.220	0.245	0.270
A2	0.355	0.380	0.405
D	1.660	1.690	1.720
D1	1.000 REF		
E	1.660	1.690	1.720
E1	1.000 REF		
b	0.285	0.310	0.335
e	0.500 REF		
x1	0.345 REF		
x2	0.345 REF		
y1	0.345 REF		
y2	0.345 REF		

Revision History and Checking Table

Version	Date	Revision Item	Modifier	Function & Spec Checking	Package & Tape Checking
1.0	2018-12-18	Preliminary Version	Yang Zhen	Yang Zhen	Zhu Jun Li
1.1	2019-4-29	Detail Description	Sun Si Bing	Sun Si Bing	Zhu Jun Li
1.2	2019-8-15	1.Add in_power_good and char finish interrupt signal; 2.change CHAR_EN from 1b(enable) to 0b(disable) 3.change TRICKLE_CHAR_ISET[2:0] from 101b(22mA) to 001b(2mA) 4.change IN_EXIT_SHIP_TSET from 1b(2s) to 0b(50ms); 5.Add INT port input and output function enable control bit; 6.Change Exit shipping mode method (add signal edge and timer judgement)	Sun Si Bing	Sun Si Bing	Zhu Jun Li
1.3	2019-12-04	1.Add SYS discharge and INT function description. 2.Modify I _{BAT} parameter in electrical characteristics	Xia Yong Jie	Xia Yong Jie	Zhu Jun Li
1.4	2020-2-13	Add I _{IN2} 、I _{IN3} parameter	Xia Yong Jie	Xia Yong Jie	Zhu Jun Li
1.5	2020-3-10	Add 90mA, 10mA charge current parameter, adjust BAT to SYS current limit	Xia Yong Jie	Xia Yong Jie	Zhu Jun Li
1.6	2020-06-16	Update charge current step to 8mA	Xia Yong Jie	Xia Yong Jie	Zhu Jun Li
1.7	2023-05-08	1.Update Typeset 2.Add termination current register and BAT to SYS discharge current Limit register note description	Yin Peng	Xia Yong Jie	Liu Jia Ying
1.8	2023-10-23	Add Marking	Shibo	Xia Yong Jie	Liu Jia Ying